

New Methods for Tight Analysis of Population-based Evolutionary Algorithms

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Evolutionary Algorithms (EAs)

EAs are **random search heuristics** which are based on the concepts of the natural evolution:

- ▶ Mutation
- ▶ Crossover
- ▶ Selection
- ▶ Populations

Generic EA Scheme



Image source (downloaded in 2013): <http://physiol.gu.se/maberg/images.html>

Generic EA Scheme

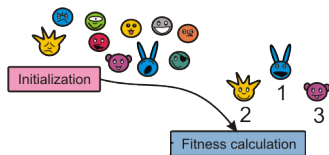


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Generic EA Scheme

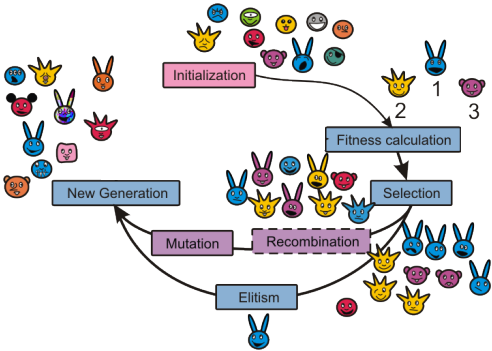


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Generic EA Scheme

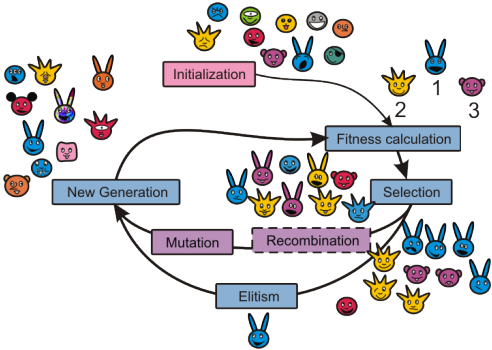


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Generic EA Scheme

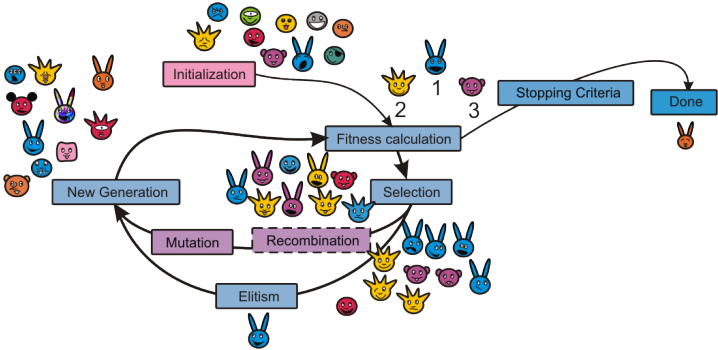


Image source (downloaded in 2013): <http://physiol.gu.se/maberg/images.html>

Theory and Practice

Practice:

- ▶ **Can** solve hard problems with EAs
- ▶ **Needs** some advice on how to tailor an algorithm for a problem

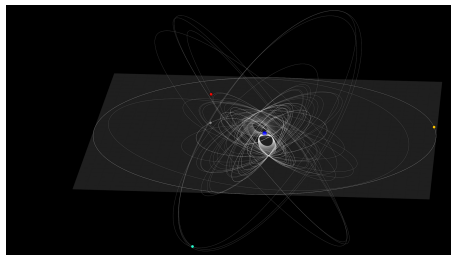
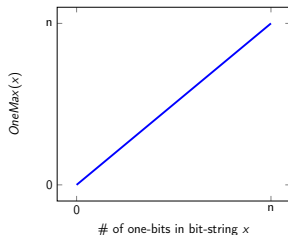


Illustration of the winner of GTOC 8 contest (image source: <https://www.esa.int>)

Theory:

- ▶ **Cannot** analyse complicated problems
- ▶ **Can** give some valuable advice based on the analysis of easy problems



Goals of Theoretical Studies

- ▶ Understand working principles of EAs
- ▶ Improve existing EAs
- ▶ Propose new effective EAs

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The **main tool** of the theory is the **runtime analysis** via mathematical means

The Focus of the Thesis

We aim at the better understanding of the **population-based EAs**

- ▶ **Complicated** stochastic processes behind them
 - ▶ **Lack of tools** for their analysis
- ▶ Only **few** theoretical results existed
- ▶ Subject of great interest for **practitioners**

Contribution of the Thesis

New analysis methods

- ▶ The new method of the complete trees
- ▶ The new method for the analysis of no-drift processes
- ▶ Method for the precise analysis on plateaus
- ▶ New additive drift theorem with tail bounds

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- ▶ The fast $(1 + (\lambda, \lambda))$ GA

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New theoretical results

- ▶ Recommendations on how to set up parameters of EAs

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Parameters and Performance

Rally cars have multiple parameters which can be adjusted

- ▶ Breaks balance
- ▶ Transmission speed ranges
- ▶ Tires
- ▶ ...



Picture source:

<https://toyotagazooracing.com/wrc/>

Question: how to set the parameters for the best performance?

Recommendations from the Thesis Results

Static parameters choices

- ▶ **Population size** for the $(\mu + \lambda)$ EA: $\mu = O(\log(n))$ and $\lambda = O(\mu)$
- ▶ **Population size** for the (μ, λ) EA: $\mu \approx e\lambda$ and $\mu = \Omega(n^{3/4})$.
- ▶ When traversing plateaus of radius k : **mutation rate** should be $\frac{k}{en}$
- ▶ For the $(1 + (\lambda, \lambda))$ GA on JUMP_k : non-standard **parameter setting**
 $p = c = \sqrt{\frac{k}{n}}$ and $\lambda = \sqrt{\frac{n^k}{k}}$.

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Dynamic parameters choices

- ▶ We can effectively choose parameters **randomly** from a specific distribution (with proper scaling)
- ▶ After the thesis: we can do it with multiple parameters simultaneously

Summary

- ▶ In the thesis we proposed several new **analysis methods**
- ▶ With them we obtained some recommendations for the **practical use of EAs**
- ▶ We also proposed a new algorithm with the dynamic parameters choices and showed its efficiency on multiple problems

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Thank you!